

CHCNAV

APACHE 3 PRO

COMPACT HYDROGRAPHIC DRONE



MARINE SURVEY
& CONSTRUCTION

ADVANCED USV FOR BATHYMETRIC SURVEY

The APACHE 3 Pro is a compact, professional unmanned surface vehicle (USV) designed for autonomous bathymetric surveys in shallow waters. Its double-layered carbon fibre hull provides exceptional impact resistance and unsinkability. The IP67 rating guarantees dust and water tightness, protecting on-board components under all circumstances. The semi-recessed motor reduces water resistance, improves endurance, and allows speeds up to 6 m/s.

The Apache 3 Pro GNSS RTK + inertial navigation system ensures highly accurate measurements even when the GNSS signal is temporarily interrupted, such as when navigating under a bridge. The built-in CHCNAV D270 echo sounder provides the most reliable and accurate depth measurements at all times.

LIGHTWEIGHT DESIGN

The APACHE 3 Pro is constructed from macromolecular polyester carbon fibre and Kevlar glass fibre, resulting in a remarkably light weight of only 10 kg (excluding sensors). This design allows a single operator to effortlessly manage a variety of remote deployment scenarios, ensuring versatility and ease of use in a wide range of operating conditions.

ENABLING SURVEYS IN DIVERSE WATER CONDITIONS

The semi-recessed motor and innovative internal rotor motor design provide the APACHE 3 Pro with a shallower draft, improving the USV's ability to navigate in different water depths. The motor design provides enhanced protection, reducing the risk of damage and ultimately extending the motor's service life.

REAL-TIME DATA FOR GREATER SECURITY AND PRODUCTIVITY

A combination of SIM, and network bridge with automatic switching capabilities ensures reliable communications. In addition, cloud-based remote monitoring is seamlessly integrated to provide real-time information on the status of the Apache 3 Pro, enhancing its control and security. The use of 4G and 2.4G networks eliminates distance limitations and enables efficient data exchange in a variety of operating environments.

MILLIMETER WAVE AUTOMATIC OBSTACLE AVOIDANCE

The APACHE 3 Pro comes standard with a millimetre-wave obstacle avoidance system to detect obstacles within a wide 110° angle ahead. When it encounters an obstacle, the USV autonomously charts a detour course to navigate around the obstacle, effectively minimising the potential risk of collision damage during operation.

MAINTAIN HIGH ACCURACY UNDER BRIDGE

APACHE 3 Pro ensures consistent accuracy even when navigating under bridges. If the GNSS signal is lost, the USV maintains its course by automatically navigating under bridges and continuously providing high-precision position data. Accurate position and attitude data also compensates for the effects of hull sway on survey results. Tight integration of GNSS and INS data eliminates outliers and improves the reliability of the information collected.

SINGLE-BEAM ECHOSOUNDER FOR BATHYMETRIC SURVEY

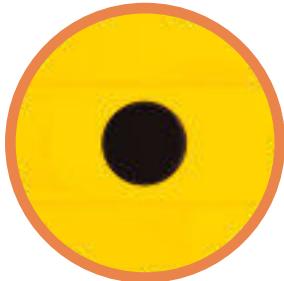
APACHE 3 Pro comes standard with D270 single beam echo sounder. It is portable and integrates a built-in water temperature sensor to enable real-time correction of sound velocity in response to temperature changes, resulting in superior depth measurement accuracy.



COMPACT
TURNKEY
USV SYSTEM



Motor



Transducer



360° Camera



Millimetre Wave Radar

SPECIFICATIONS

Physical		Positioning	
Hull dimension (L x W x H)	1.05 m x 0.55 m x 0.39 m	Satellite system	BDS B1/B2, GPS L1/L2, GLONASS L1/L2, Galileo E1/E5, QZSS
Material	Macromolecule polyester carbon fibre	Channel	432
Weight (w/o instrument and battery)	10 kg	Single point position (RMS)	Horizontal: 1.5 m Vertical: 2.5 m
Maximum payload	30 kg	DGNSS positioning accuracy	Horizontal: 0.4 m + 1 ppm Vertical: 0.85 m + 1 ppm
Anti-wave & Wind	3 rd wind level and 2 nd wave level	RTK positioning accuracy	Horizontal: ±8 mm + 1 ppm Vertical: ±15 mm + 1 ppm
Hull design	Triple-hull vessel	Heading accuracy	0.2 °@1 m baseline
Waterproof	IP67	Inertial navigation stability	6 ‰ h (Accuracy attenuation 1 m after 20 s)
Draft	9 cm	IMU update rate	200 Hz
Indicator light	Two-color light (Display positioning signal)	D270 Single Beam Echo Sounder	
Video	360° omnidirectional video	Data type	CHCGD ⁽¹⁾ , NMEA SDDPT/SDDBT, original waveform
Auto-return	Auto-return while low battery or signal loss	Operating system	Linux
Obstacle avoidance	Millimetre wave automatic obstacle avoidance	OLED display	1.46 inch
Obstacle avoidance range	0.2 ~ 40 m Horizontally & vertical angle: 112° x 14°	Wi-Fi	802.11n 2.4 GHz
Power		Bluetooth	BT5.0, downward compatible to BT2.x
Type	Electric	Weight	0.84 kg
Propeller type	Brushless DC	Sounding range	0.15 m to 200 m
Direction control	Veering without steering engine	Supply voltage	±0.01 m + 0.1% x D (D is the depth of water)
Maximum motor power	800 W	Resolution	0.01 m
Maximum motor speed	7,200 rpm/min	Frequency	200 kHz
Motor installation	Pluggable	Beam angle	6.5° ± 1°
Li-ion battery capacity	24,500 mAh, 36 V x 5	Waterproof	IP67
Power supply	Support single battery independent power supply or dual battery balanced power supply	Water temperature	-55°C~+100°C, real-time correction of the sound speed
Battery replacement	Support hot swap	Maximum transmit power	300 W
Battery endurance	2 x 3 h@2 m/s (running on 2 battery sets)	Power consumption	10 W
Maximum speed	6 m/s		
Communication		* Specifications are subject to change without notice. (1) CHCGD is CHCNAV format.	
Data communication	Network bridge: 1 km and 4G: unlimited		
R/C communication	2.4 GHz		
Remote control range	1 km		
SIM card slot	Nano SIM		
Interface	2 x RJ45 network port 2 x RS232 serial port 1 x RS485 serial port 1 x PPS		
Navigation mode	Manual or Auto-Pilot		
Waterproof of master control	IP67		
Data storage	Local storage (multi-channel storage) & Remote storage		

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