

# APACHE 3 PRO

## COMPACT HYDROGRAPHIC DRONE



**MARINE SURVEY  
& CONSTRUCTION**

# ADVANCED USV FOR BATHYMETRIC SURVEY

The APACHE 3 Pro is a compact, professional unmanned surface vehicle (USV) designed for autonomous bathymetric surveys in shallow waters. Its double-layered carbon fibre hull provides exceptional impact resistance and unsinkability. The IP67 rating guarantees dust and water tightness, protecting on-board components under all circumstances. The semi-recessed motor reduces water resistance, improves endurance, and allows speeds up to 6 m/s.

The Apache 3 Pro GNSS RTK + inertial navigation system ensures highly accurate measurements even when the GNSS signal is temporarily interrupted, such as when navigating under a bridge. The built-in CHCNAV D270 echo sounder provides the most reliable and accurate depth measurements at all times.

## LIGHTWEIGHT DESIGN

The APACHE 3 Pro is constructed from macromolecular polyester carbon fibre and Kevlar glass fibre, resulting in a remarkably light weight of only 10 kg (excluding sensors). This design allows a single operator to effortlessly manage a variety of remote deployment scenarios, ensuring versatility and ease of use in a wide range of operating conditions.

## ENABLING SURVEYS IN DIVERSE WATER CONDITIONS

The semi-recessed motor and innovative internal rotor motor design provide the APACHE 3 Pro with a shallower draft, improving the USV's ability to navigate in different water depths. The motor design provides enhanced protection, reducing the risk of damage and ultimately extending the motor's service life.

## REAL-TIME DATA FOR GREATER SECURITY AND PRODUCTIVITY

A combination of SIM, and network bridge with automatic switching capabilities ensures reliable communications. In addition, cloud-based remote monitoring is seamlessly integrated to provide real-time information on the status of the Apache 3 Pro, enhancing its control and security. The use of 4G and 2.4G networks eliminates distance limitations and enables efficient data exchange in a variety of operating environments.

## MILLIMETER WAVE AUTOMATIC OBSTACLE AVOIDANCE

The APACHE 3 Pro comes standard with a millimetre-wave obstacle avoidance system to detect obstacles within a wide 110° angle ahead. When it encounters an obstacle, the USV autonomously charts a detour course to navigate around the obstacle, effectively minimising the potential risk of collision damage during operation.

## MAINTAIN HIGH ACCURACY UNDER BRIDGE

APACHE 3 Pro ensures consistent accuracy even when navigating under bridges. If the GNSS signal is lost, the USV maintains its course by automatically navigating under bridges and continuously providing high-precision position data. Accurate position and attitude data also compensates for the effects of hull sway on survey results. Tight integration of GNSS and INS data eliminates outliers and improves the reliability of the information collected.

## SINGLE-BEAM ECHOSOUNDER FOR BATHYMETRIC SURVEY

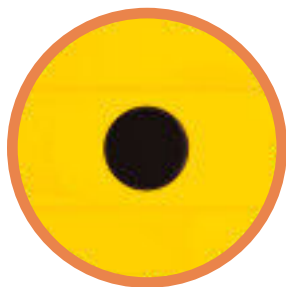
APACHE 3 Pro comes standard with D270 single beam echo sounder. It is portable and integrates a built-in water temperature sensor to enable real-time correction of sound velocity in response to temperature changes, resulting in superior depth measurement accuracy.



**COMPACT  
TURNKEY  
USV SYSTEM**



**Motor**



**Transducer**



**360° Camera**



**Millimetre Wave Radar**

# SPECIFICATIONS

| Physical                            |   |
|-------------------------------------|---|
| Hull dimension (L × W × H)          | 1.05 m x 0.55 m x 0.39 m                                  |
| Material                            | Macromolecule polyester carbon fibre                      |
| Weight (w/o instrument and battery) | 10 kg   |
| Maximum payload                     | 30 kg   |
| Anti-wave & Wind                    | 3 <sup>rd</sup> wind level and 2 <sup>nd</sup> wave level |
| Hull design                         | Triple-hull vessel  |
| Waterproof                          | IP67  |
| Draft                               | 9 cm  |
| Indicator light                     | Two-color light (Display positioning signal)              |
| Video                               | 360° omnidirectional video                                |
| Auto-return                         | Auto-return while low battery or signal loss              |
| Obstacle avoidance                  | Millimetre wave automatic obstacle avoidance              |
| Obstacle avoidance range            | 0.2 ~ 40 m<br>Horizontally & vertical angle: 112° x 14°   |

| Power                   |   |
|-------------------------|---|
| Type                    | Electric  |
| Propeller type          | Brushless DC  |
| Direction control       | Veering without steering engine   |
| Maximum motor power     | 800 W   |
| Maximum motor speed     | 7,200 rpm/min   |
| Motor installation      | Pluggable   |
| Li-ion battery capacity | 24,500 mAh, 36 V x 5  |
| Power supply            | Support single battery independent power supply or dual battery balanced power supply |
| Battery replacement     | Support hot swap  |
| Battery endurance       | 2 x 3 h@2 m/s (running on 2 battery sets)   |
| Maximum speed           | 6 m/s   |

| Communication                |  |
|------------------------------|--|
| Data communication           | Network bridge: 1 km and 4G: unlimited   |
| R/C communication            | 2.4 GHz  |
| Remote control range         | 1 km   |
| SIM card slot                | Nano SIM   |
| Interface                    | 2 x RJ45 network port<br>2 x RS232 serial port<br>1 x RS485 serial port<br>1 x PPS |
| Navigation mode              | Manual or Auto-Pilot   |
| Waterproof of master control | IP67   |
| Data storage                 | Local storage (multi-channel storage) & Remote storage                             |

| Positioning                   |  |
|-------------------------------|--|
| Satellite system              | BDS B1/B2, GPS L1/L2, GLONASS L1/L2, Galileo E1/E5, QZSS |
| Channel                       | 432  |
| Single point position (RMS)   | Horizontal: 1.5 m<br>Vertical: 2.5 m                     |
| DGNSS positioning accuracy    | Horizontal: 0.4 m + 1 ppm<br>Vertical: 0.85 m + 1 ppm    |
| RTK positioning accuracy      | Horizontal: ±8 mm + 1 ppm<br>Vertical: ±15 mm + 1 ppm    |
| Heading accuracy              | 0.2 °@1 m baseline                                       |
| Inertial navigation stability | 6 7 h (Accuracy attenuation 1 m after 20 s)              |
| IMU update rate               | 200 Hz   |

| D270 Single Beam Echo Sounder |  |
|-------------------------------|--|
| Data type                     | CHCGD <sup>(1)</sup> , NMEA SDDPT/SDDBT, original waveform |
| Operating system              | Linux  |
| OLED display                  | 1.46 inch  |
| Wi-Fi                         | 802.11n 2.4 GHz  |
| Bluetooth                     | BT5.0, downward compatible to BT2.x                        |
| Weight                        | 0.84 kg  |
| Sounding range                | 0.15 m to 200 m  |
| Supply voltage                | ±0.01 m + 0.1% x D<br>(D is the depth of water)            |
| Resolution                    | 0.01 m   |
| Frequency                     | 200 kHz  |
| Beam angle                    | 6.5° ± 1°  |
| Waterproof                    | IP67   |
| Water temperature sensor      | -55°C~+100°C, real-time correction of the sound speed      |
| Maximum transmit power        | 300 W  |
| Power consumption             | 10 W   |



\* Specifications are subject to change without notice.  
(1) CHCGD is CHCNAV format.

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